

MMME2044 Individual Design

Gearbox Actuator

Clinic session for CDR

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Observation from PDR submission

Where you're doing well

- Good understanding of requirements (SoR)
- Concept generation and selection using morphology chart and decision matrix table
- Calculation of power, torque and forces, etc
- Embodiment design from some submissions

Where improvement may be made

- Detailed calculations for spring selection and actuator sizing
- Embodiment and detail design so as to start Solidworks modelling and GA/detail drawings

Outline of session

The purpose of the CDR clinic session is

- to discuss and clarify questions from PDR submission
- to give an outline for CDR submission
- to show examples on design and calculations
- to recap a few points, e.g. GA and detail drawings
- to remind a few items for productive working toward CDR submission

Critical Design Review (CDR)

The CDR submission is to present

- a satisfactory design solution to meet stated requirements,
- a complete record/documentation of the project to date.

The CDR report should be presented using the provided CDR pro-forma

- Executive summary (1 page, max 300 words)
- Engineering and design rationale (including updated Statement of Requirements and Morphology chart using pro-forma) (2~3 pages)
- Materials selection (1~2 pages)
- Calculations (2~4 pages)
- GA (General Arrangement) drawings (one the Actuator alone and the other showing the Actuator assembled onto the Gearbox) (2 pages)
- > Detail drawings of Actuator casing and actuating shaft (piston rod) (2 pages)
- Time management (using Student Guidelines pro-forma) (1 page)
- Appendices (optional)

Note: It is useful to refer to Project Brief file.

Individual Design CDR submission on Moodle

- > The deadline for CDR submission on Moodle is 3:00pm, Friday, 31st March.
- The CDR report is a Summative submission. It is worth 30% of the MMME 2044 module.
- The CDR pro-forma and template folders/files will be available in the Individual Design Project folder in the <u>Design Tutorial and Feedback section</u> on Moodle.
- Make sure your CDR report (a single file in PDF format) is compiled in a clear and concise manner to recommended pages.
- Place your CDR report, spreadsheet/hand-written files and Solidworks models and drawings in separate folders as from the template folder.

Executive summary (1 page per group, 300 words max)

- Give a CONCISE summary of your individual design solution of the Gearbox Actuator,
 - A summary of the actuator design if it meets all requirements
 - A very brief discussion on specific features for proper function and considerations for easy manufacturing, assembly and operation

Table of content (optional)

Engineering and Design Rationale (2~3 pages max)

- Present an updated statement of requirements using pro-forma.
- Present your rationale and assessment to the following questions:
 - How does the Actuator work?
 - Are all design requirements met?
 An updated morphology chart showing how the Final Design meets requirements
 - What are the strengths and weaknesses of the design?
 - Can the design be easily manufactured, assembled and operated in all possible operational conditions?

Engineering and Design Rationale (cont'd)

> You may use Solidworks assembly **images and/or cutaway views** to identify key parts and design features and to describe how the air motor operates for the intended functions. B-3 Mounting of the cylinder/crankcase

B-4 Interfaces:

Starter assembly

interface

Interfaces were created to accommodate the ancillary devices onto the engine block. This allows for easy assembly and attachment. The following figures show two isometric views of the engine block, which shows the interfaces.

Exhaust

interface

Flange feature

To ensure proper alignment of the piston head to the crankcase, a circular sleeve feature has been added which provides proper mounting which fits into the crankcase.a flange feature has been embodied in the design and 4 M5 bolths will be used to connect the cylinder heaad to the crankcase. The following figure is a cross section of the engine block showing all of the designed components along with the mounting of the bearings.

circular sleeve feature

Compartment to

locate seals and

seal

bearings

Small gap (1 mm) between bearing and



An example of individual design: 2-stroke engine (available on Moodle)

Calculations (2~4 pages)

- Sumarise calculation results supported by spreadsheet with clear annotations in the template folder (see <u>spreadsheet of ASME shaft design</u> on Moodle)
 - Updated spring calculations (<u>see Lecture slides for preparing PDR</u>)
 - Stress calculation of the cylinder and other parts under severe loading
 - Bolted joints and tightening torque
 - Selection of seals

Circumferential and longitudinal stresses of a hydraulic cylinder (thin-walled vessel as from MMME1028)

- Hoop (circumferential) stress:
- Longitudinal (axial) stress:
- Pin or bolt under double shear loading

• Shear stress:
$$au = rac{1}{2}rac{P}{A}$$
, $A = rac{\pi}{4}d^2$ $rac{P}{d}$ - force diameter



Calculations

- Reserve factors (also called Safety factor)
- 1) Understand loading condition of key parts and decide initial dimensions;
- 2) Calculate axial or shear force, torque or bending moment;
- **3)** Select a suitable material/heat treatment and find material properties, e.g. yield strength (*δy*), endurance limit stress (*δe*);
- 4) Calculate max stresses, e.g. max stress (*δmax*) under tension or bending, or max shear stress (*τmax*) due to torsion or direct shear;
- 5) Calculate the reserve factor, $n_{rf} = \sigma_r$ or $\sigma_e / \sigma_{max} \ge 1$ or $n_{rf} = \tau_r$ or $\tau_e / \tau_{max} \ge 1$ or a given value; if not, go back to 2) or 4) and iterate until an optimum solution obtained.
- **Tresca (max shear) yield criterion** :
- von Mises (max strain energy) yield criterion:

$$\tau_y = \frac{1}{2}\sigma_y$$

$$\tau_y = \frac{1}{\sqrt{3}}\sigma_y = 0.577\sigma_y$$

 au_y is shear stress at yielding and σ_y is tensile yield strength (same Eqs apply to endurance limits)

Worked example: Joint design for a 2-stroke engine

(A worked example from Bolted joints Lecture slides 49~52)

- **Design bolted joint for the cylinder & casing of a** 2-stroke engine.
 - Peak force is **P** = 6.5 kN
 - A **permanent joint** with a threaded grip length *It* = 25 mm
 - Cylinder and crankcase are made of cast Al (E=70 GPa)
 - 4 x bolts (5.6 or similar, carbon steel, E=200 GPa)
 - **Reserve factor** should be at least **1.5**.
 - Determine
 - a) Suitable size of socket cap screw
 - b) Right amount of tightening torque

Otto cycle of two-stroke engine

https://en.wikipedia.org/wiki/Twostroke_engine



Worked example: Joint selection of a 2-stroke engine

a) Selection of a suitable socket cap screw

Bolted joint Part 3

- Joint design specifies external load (*P=6.5 kN*) and reserve factor (*n₀=1.5~2*), a 1. permanent joint of 4 x socket cap screw (N=4).
- 2. Choose a suitable bolt size from BS ISO 898-1: 2009 (Table 5)

Select M4 and a property class of 5.6,

For a non-permanent joint,

For a permanent joint, $F_i = 0.9 \times A_S \sigma_p$

$$F_i = 0.75 \times A_S \sigma_p$$

Table 5 — Proof loads — ISO metric coarse pitch thread

As no maintenance required,

 $F_i = 0.9 \times A_S \sigma_P = 0.9 \times F_P$ $= 0.9 \times 2,460 = 2,214(N)$

	Nominal	Property class						
Thread a	area	4.6	4.8	5.6	5.8	6.8	8.8	9.8
	A _{s,nom} b mm²				Proof load, $F_p (A_{s,nom} \times S_{p,nom})$, N			
M3 M3 5	5,03 6,78	1 130 1 530	1 560 2 100	1 410	1 910 2 580	2 210 2 980	2 920 3 940	3 270 4 410
M4	8,78	≺1 980	2 720	2 460	3 340	3 860	5 100	5 710
M5 M6 M7	14,2 20,1 28,9	3 200 4 520 6 500	4 400 6 230 8 960	3 980 5 630 8 090	5 400 7 640 11 000	6 250 8 840 12 700	8 230 11 600 16 800	9 230 13 100 18 800
	1	I	I		I	I	I	I

Worked example: Joint selection of a 2-stroke engine

3. Calculate stiffness of the **bolts & components** (*Kb* & *Kc*):

$$K_b = \frac{A_s E}{l_t} = \frac{8.78 \times 200 \times 10^3}{25} = 70.2 \times 10^3 (N/mm)$$

Assume a "hard joint", i.e. *Kc* = 3 *Kb*, so, $K_c = 3 \times K_b = 210.6 \times 10^3 (N/mm)$ **Note:** The same approach may be used in the **Gearbox Actuator calculations**.

4. Calculate max external load (*Po*) without separation (Bolted joints Lecture slide 39):

$$P_0 = NF_i \frac{K_b + K_c}{K_c} = 4 \times 2,214 \times \frac{(70.2 + 211.3) \times 10^3}{211.3 \times 10^3} = 11,790(N)$$

- 5. Calculate the Reserve factor (*no*): $n_0 = \frac{P_0}{P} = \frac{11,790}{6,500} = 1.8 > 1.5$
- 6. Tightening torque (Bolted joints Lecture slide 27):

 $T = kF_i d = 0.2 \times 2,214 \times 0.004 = 1.8 (Nm)$

K ≈ 0.2; *Fi* is pre-tension force (N), *d* is diameter (m)

Therefore, 4x M4 (5.6) screws are acceptable. If not, either choose M5 cap screw or higher

Bolted joint Part 3

grade, e.g. 5.8, 6.8, 9.8

Note: Above Eq. is a simplification of the **power screw formula** from Dr Johnson's lecture in MMME1024.

Metric thread tensile area and mechanical properties

Bolted joint Part 2

• BS EN ISO 898-1: 2013 Mechanical properties of fasteners made of carbon and alloy steels (Bolted joint Lecture slide 11)



Worked example: "O" ring selection for Air motor piston

Select suitable "O" rings & Groove dimensions (based on BS 4518) Refer Seals Lecture slides & worked examples to select an "O" ring. You may also use James Walker and ClaronPolysea[®] catalogues available on Moodle to select suitable seals.

- "O" ring grooves cut in piston (shaft).
- From BS4518 Table 1 (available on Moodle and Seals Lecture handbook), 0116-24 is suitable for a φ16 mm piston.
- 0116-24 "O" rings CAD model is available from Solidworks Toobox BSI part library or you can create yourself.







Worked example: "O" ring selection for Air motor piston

Select a suitable "O" ring Groove dimensions (Groove in piston)

Table 1 — Dimensions of "O"-rings (see Figure 1) and related nominal housing diameters for diametral sealing (see Figure 2)

All dimensions in millimetres

<u>+</u>	"O"-ring ref. no (see note)		"O"-ring d	Nominal housing dimensions (see Figure 2 and 4.1)			
diameter A		Internal diameter <i>B</i>	Internal diameter tolerance	Section diameter A	Section diameter tolerance	$\begin{array}{c} {\rm Shaft\ diameter} \\ d_1 \end{array}$	Cylinder diameter D1
	0031-16	3.1		1.6		3.5	6
0116-24	0041-16	4.1		1.6		4.5	7
	0096-24 ^a	9.6		2.4		10 ^b	14
	8106-24 ^a	10.6		2.4		11	15
φ11.6 mm	0116-24 ^a	11.6		2.4		12 ^b	16 ^b
$\phi 2.4 \text{ mm}$	0126-24 ^a	12.6		2.4		13	17
φ 2. τ	0136-24 ^a	13.6	± 0.2	2.4	± 0.08	14 ^b	18

"O" ring groove dimensions Depth **F** = 2.13~2.20 Width **E** = 3.2+0.2 Clearance Gmax = 0.14 Chamfer C = 0.6

 $\mathsf{B}=\phi\,\mathsf{11}.$ $A = \phi 2.4$

Internal

diameter **B**

57

Section XX

Radius $\mathbf{R} = 0.5$

Table 4 Groove Dimensions for pneumatic applications

All dimensions in millimetres

"O"-ring ref. no.	Cross section	Radial depth F		Groove width	Total diametral	Lead-in chamfer	Max. radius <i>R</i>
	diameter A	max.	min.	E 0.2	G (max.)		
0036-24 to 0176-24	(2.4)	2.20	2.13	3.2	0.14	0.6	0.5
0195-30 to 0445-30	3.0	2.77	2.70	4.0	0.15	0.7	1.0
0443-57 to 1443-57	5.7	5.38	5.22	7.5	0.18	1.0	1.0
1441-84 to 2491-84	8.4	7.96	7.75	11.0	0.20	1.2	1.0

Worked example: "O" ring selection of a pneumatic cylinder

Select "O" rings for cylinder dia D1=Ø25 mm and piston rod dia d1= Ø10 mm:

• For Cylinder: from Table 1, 0221-16, 0206-24 and 0195-30 are all ok but only 0195-30 is suitable for pneumatic applications.

• For Piston rod: from Table 1, <u>0096-24</u> is suitable for the piston rod.



• Material selection

- > A summary of the selected materials for the designed parts
- Use of material data in calculations including the weight of the Actuator (using Solidworks).
- Considerations should be given to
 - Performance, strength, wear resistance, lightweight and cost
 - Suitable routes/processes for manufacturing
- Some practical points
 - You may use CES software data in calculations and support decision making but not to present irrelevant CES bubble charts.
 - It is a good idea to <u>use a table</u> to summarise the selected materials for designed parts, manufacture processes and material data to be used in calculation/evaluation.

- Material selection (Generic approach covered in MMME2045)
 - Carbon and alloy steels are commonly used power transmission components,
 e.g. crankshaft, shafts, gears, pistons, piston rods, fasteners, etc.
 - AISI/SAE designation by Four digits (xxyy with xx to define alloy type & yy to specify carbon contents),

e.g. **1020** - low carbon steel with **0.2% carbon**, **4140** - chromium molybdenum steel & **4340** - nickel chromium molybdenum steel both with **0.4% carbon**.

- High strength Aluminium alloy, e.g. Al7075-T6 (temper heat treated) can be used for cylinders in lightweight and corrosion resistance applications.
- Cast iron of various types can be used for cylinders below 10 MPa pressure, e.g. Gray cast iron (ASTM A48) used for engine and gearbox casing, flywheel, etc.
- See additional slides on Materials and Heat Treatment by Prof Geoff Kirk (available in the Individual Design Project section on Moodle)

• Heat treatments

Heat treatment is a process of heating and cooling at different rates to achieve desired mechanical properties through microstructural changes and phase transformation

Common heat treatment methods

- Annealing: heating followed by slow cooling for good machinability
- Normalizing: heating steel to certain temperature and cooling in still or circulated air to obtain a uniform microstructure
- Quenching and Tempering: heating a part to austenite state followed by rapid cooling (quenching) and then reheated (tempered) to a lower temperature for a good combination of hardness and ductility
- Through-hardening: a heat treatment including annealing, normalizing, and quenching and tempering
- In the Gearbox Actuator project, you need to use appropriate material properties via a suitable heat treatment

Worked example: select material for piston rod

- Effective use of CES software (Cambridge Engineering Selector, from MMME2045)
 - Piston rod: AISI 4340, a low alloy steel (Ni-Cr-Mo) for high tensile application



Number of Cycles

Stress Ratio=-1

irrelevant or superfluous material, e.g. CES bubble charts!

- Manufacturing processes
 - Power transmission components, e.g. gears, shafts, piston/piston rod and casings are typically manufactured by a route of shaping (e.g. casting, forging, machining and grinding), heat treatments for enhanced properties and surface processing (e.g. polishing and coating) operations.
 - Primary shaping processes: e.g. forging, extrusion, casting, rolling
 - Machining processes: manual or CNC machining/turning, milling, drilling
 - Finishing processes: grinding, polishing, coating
 - In the Gearbox Actuator project, only main manufacturing steps should be considered to designed parts, e.g. the piston, piston rod/shaft, casing/cylinder

Assembly drawings (2 A3 drawing sheets)

- One GA drawing to show the assembled Gearbox Actuator alone with BOM, Part List table, necessary fits and assembly instructions. Another GA to show the Actuator mounted on the Gearbox casing.
- The GA drawings should show clearly the detailed design of the air motor using sections, views and partial views if necessary. The GA drawings should also include all title block information to BS 8888 standard.
 - Appropriate choice of views, including placement of cross sections and use of detailed views to show smaller details at larger scale.
 - Appropriate use of ISO standard fits on any critical interfaces between components.
 - Appropriate exclusions of features from cross-sections, i.e. fasteners and features with no internal details such as solid shafts.
 - Appropriate selection of cross-section hatch spacing and angle to show separation of adjacent parts.
 - $\circ~$ Appropriate placement of BOM table and BOM balloons.
 - Appropriate notation of critical fits between components.

Assembly drawings (cont'd)

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An example GA of a roller-subassembly (check CAE3 Task for details on Moodle)



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Assembly drawings (cont'd)

Fits specification using BS 4500A (Hole Basis) (available on Moodle)

Fits are defined to ensure proper function of a machine system:

- Clearance fits: shaft smaller than hole to leave a clearance
- Transition fits: shaft slightly bigger or smaller than hole for an interference or clearance
- Interference fits: shaft bigger than hole to prevent relative motion



Specification of Fits in GA and Tolerances in Detail Drawings Roller-Sub Assembly as an example (Use BS4500 A)



Note: BS 4500A & BS 4500B charts are available on Moodle

ONLY TWO detail drawings (Actuator casing and shaft/piston rod)

NO cutting list, process sheets or manufacturing plan as this is a design task

- A detail drawing should include all the necessary information required for the definition of the part, e.g. material, properties, dimensions and tolerances.
- Dimensions and tolerances are clearly defined for intended function, easy manufacturing and inspection with datum feature established.
- A complete set of required dimensions, drawn from appropriate datums.
- Tolerances on all dimensions that have a specified fit in the GA drawing.
- Appropriate part naming conventions matching the GA bill of materials.

Detail drawings and process sheets (cont'd)

Roller-subassembly: Detail drawing of the Shaft



Roller subassembly from 1st year EDP (see CAE 3 brief slides and SW models on Moodle



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A few more items for CDR submission

- Use SW models of M8 oil union & seal washer available on Moodle
- Use <u>https://www.leespring.co.uk/</u> to download SW models of disc or compression springs or create SW models yourself
- Use SW Toolbox to access standard parts, e.g. BS4518 "O" rings, Bolts, nuts and washers, circlips & set screws
- Make sure the Actuator is properly mounted on Gearbox casing and connected to Gearbox clutch fork
- Compile SW models and files using the template folders

SW Toolbox standard parts of "O" rings, circlips and fasteners



M8 oil union & seal washer



Leespring Disc & coil spring SW models



What to do next?

- Start working on Solidworks modelling, GA and detail drawings
- Update engineering calculations and material selection sections
- Work effectively with **your tutor** in **Design sessions in the coming weeks**
- Work on your **CDR report using the pro-forma** in a clear and concise manner
- Organise all the files, CDR report, SW models and spreadsheet files
- Attend the CAE and Project Support sessions (4-6pm, Fridays in Coates C19). If needed we can arrange additional support sessions
- Get ready to submit your CDR on Moodle by 3:00pm, Friday, 31st March

Please pay an attention:

- <u>Back up all your files, Solidworks models, drawings, CDR report, etc, regularly, to</u> <u>avoid sudden loss of data (not a reason for EC approval)</u>
- Be aware of University's policy on Academic integrity & misconduct, <u>check link</u>.
- Let me and/or Khaled Goher know if you have specific cases for discussion.

Feedback

- Feedback will include completed mark sheet (available on Moodle) and feedback on design in the 1st Design Session in the Spring semester
 - Satisfactory The deliverable was achieved on time to a satisfactory standard you can proceed with your final design solution.
 - Category 1 Deficiency The deliverable was not achieved or there was a major deficiency. The deficiency needs to be addressed before manufacturing sessions.
 - Category 2 Deficiency The deliverable was achieved but there was a minor deficiency to be addressed before manufacturing sessions.
 - **Observation** Items that are acceptable but **can be improved**.
- > Additional feedback sheet on CDR submission will be made available